

### Algorithms **Rubric: No Raw Loops**

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"An Algorithm is a process or set of rules to be followed in calculations or other problem-solving operations, especially by a computer." – New Oxford American Dictionary





int r = a < b ? a : b;



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What does this line of code do?



// r is the minimum of `a` and `b` int r = a < b ? a : b;





#### int r = min(a, b);



/// returns the minimum of `a` and `b` int min(int a, int b) { return a < b ? a : b;</pre> }



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When implementing an algorithm, we need to reason through each statement

- The preconditions of each statement must be satisfied by the statements before
  - Or implied by the preconditions of the algorithm
- The postconditions for the algorithm must follow from the sequence of statements



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Functions allow us to build a vocabulary focused on semantics.



Reserved.

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  - copular constructions: is\_blue
  - consider a verb if the complexity is greater than expected



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- name() not get\_name()



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- *in-out:* by lvalue-reference



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- Prefer sink argument and result to in-out arguments



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- sink: by rvalue-reference
  - For known or expected small types and to avoid forwarding references consider by-value
- *in-out:* by lvalue-reference
- Prefer sink argument and result to in-out arguments
- are used for *sink* arguments

• For known or expected small types such as primitive types, *iterators*, and *function objects* consider by-value

spans, views, iterator pairs, and so on are a way to pass a range of objects as if they were a simple argument. The value\_type of the range determines if it is a *let* (const) argument or *in-out* (not const), and input ranges

# void display(const vector<unique\_ptr<widget>>& a) { //... a[0]->set\_name("displayed"); // DONT //... }



### **Implicit Preconditions**

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  - A meaningless object should not be passed as an argument (i.e., an invalid pointer).



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vector a{0, 0, 1, 0, 1 };
erase(a, a[0]);
display(a);
```

{ 1, 0 }





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vector a{0, 0, 1, 0, 1 };
erase(a, copy(a[0]));
display(a);
```

#### { 1, 1 }



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- Example: the reference returned from vector::back()

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- A non-trivial algorithm requires iteration
  - iteration may be implemented as a loop or recursion







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  - An invariant that holds at the start of the iteration and after each step
  - A finite decreasing property where termination happens when the property is zero
- The postcondition of the iteration is the above invariant when the decreasing property reaches zero











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Removes values equal to a in the range (f, l).

values in `[f, l)` not equal to `a`

values in `[b, l)` are unspecified

template <std::forward\_iterator I, class T> auto remove(I f, I l, const T& a) -> I;







template <std::forward\_iterator I, class T> auto remove(I f, I l, const T& a) -> I {







template <std::forward\_iterator I, class T> auto remove(I f, I l, const T& a) -> I { auto b{find(f, l, a)};







#### template <std::forward\_iterator I, class T> auto remove(I f, I l, const T& a) -> I { auto b{find(f, l, a)}; if (b == l) return b;







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Adobe

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Adobe

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• For a sequence of n elements, there are n + 1 positions







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- Ways to represent a range of elements
  - Closed interval [f, l]
  - Open interval (f, l)
  - Half-open interval [f, l)
    - By strong convention, open on the right





- [p, p) represents an empty range at position p
  - All empty ranges are not equal
- Cannot express the last item in a set with positions of the same set type
- i.e., [INT\_MIN, INT\_MAX] is not expressible as a half-open interval with type int
- Think of the positions as the lines between the elements





Memory Addresses -







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- In this model, there is a symmetry with reverse ranges (l, f]
  - The dereference operation is asymmetric. dereferencing at a position p is the value in [p, p + 1)
- Half-open intervals avoid off-by-one errors and confusion about before or after
- In C and C++, half-open intervals are built into the language. For any object, a, &a is a pointer to the object, and &a + 1 is a valid pointer but may not be dereferenceable.
- Any object can be treated as a range of one element

int a{42}; copy(&a, &a + 1, ostream\_iterator<int>(cout)); 42





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  - position and sentinel: [f, is\_sentinel), i.e. NTBS



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  - pair of positions: [f, l)
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  - position and predicate: [f, predicate), use \_\_until suffix
  - position and sentinel: [f, is\_sentinel), i.e. NTBS
  - unbounded: [f, ...), limit is dependent on an extrinsic relationship



- Half-open intervals can be represented in a variety of forms
  - pair of positions: [f, l)
- position and count:  $\int f(f(t) + n)$ , use \_ n suffix
- position and predicate: [f, predicate), use \_\_until suffix
- position and sentinel: [f, is\_sentinel), i.e. NTBS
- unbounded: [f, ...), limit is dependent on an extrinsic relationship
  - i.e., the range is require to be the same length or greater than another range


































#### stable\_partition(p, l, s)







#### stable\_partition(p, l, s)







#### stable\_partition(f, p, not1(s))







#### stable\_partition(f, p, not1(s))





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stable\_partition(f, p, not1(s))
stable\_partition(p, l, s)





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stable\_partition(f, p, not1(s))
stable\_partition(p, l, s)







stable\_partition(f, p, not1(s))
stable\_partition(p, l, s)







# return { stable\_partition(f, p, not1(s)), stable\_partition(p, l, s) };





/// Gather elements in [f, l) satisfying s at p /// and returns range containing those elements /// p is within the result

template <class I, // BidirectionalIterator class S> // UnaryPredicate auto gather(I f, I l, I p, S s) -> pair<I, I>

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# stable\_partition(f, m, p) stable\_partition(m, l, p)





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# stable\_partition(f, m, p) stable\_partition(m, l, p)







# stable\_partition(f, m, p) stable\_partition(m, l, p)































#### if (n == 1) return f + p(\*f);







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A Adobe

- template <class I, // ForwardIterator</pre> class P> // UnaryPredicate auto stable\_partition(I f, I l, P p) -> I
  - auto n = l f;if (n == 0) return f; if (n == 1) return f + p(\*f);
  - auto m = f + (n / 2);
  - return rotate(stable\_partition(f, m, p), m, stable\_partition(m, l, p));







- template <class I, // ForwardIterator</pre> class P> // UnaryPredicate auto stable\_partition(I f, I l, P p) -> I
  - auto n = l f;if (n == 0) return f; if (n == 1) return f + p(\*f);
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complexity and efficiency



- complexity and efficiency
- sorting and heap algorithms





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- sorting and heap algorithms



encoding relationships between properties into structural relationships to create structured data



- complexity and efficiency
- sorting and heap algorithms

  - i.e., a < b implies position(a) < position(b)</li>

• encoding relationships between properties into structural relationships to create structured data



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- Error prone and likely to fail under non-obvious conditions
- Introduce non-obvious performance problems
- Complicates reasoning about the surrounding code



Use an existing algorithm



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  - Prefer standard algorithms if available





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- Implement a known algorithm as a general function



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#### About the artist

#### Dan Zucco

London-based 3D art and motion director Dan Zucco creates repeating 2D patterns and brings them to life as 3D animated loops. Inspired by architecture, music, modern art, and generative design, he often starts in Adobe Illustrator and builds his animations using Adobe After Effects and Cinema 4D. Zucco's objective for this piece was to create a geometric design that felt like it could have an infinite number of arrangements.

Made with







